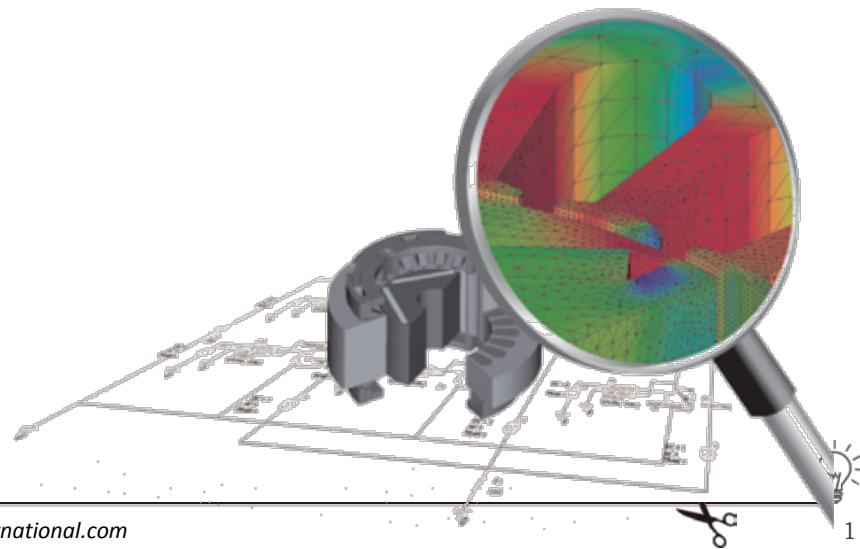


JMAG V18.0 Review of new functions

January 2019

JMAG Division

JSOL Corporation



Why JMAG V18.0?

- Get a proper vision of your geometry
- Enhancement of simulations capability
- Improve your HIL, SIL and MIL models
- Improve your loss calculations
- Better parameter handling and enhanced optimisation capability
- Think your JMAG circuit differently
- Efficiency maps directly in JMAG-Designer

Get a proper vision of your geometry

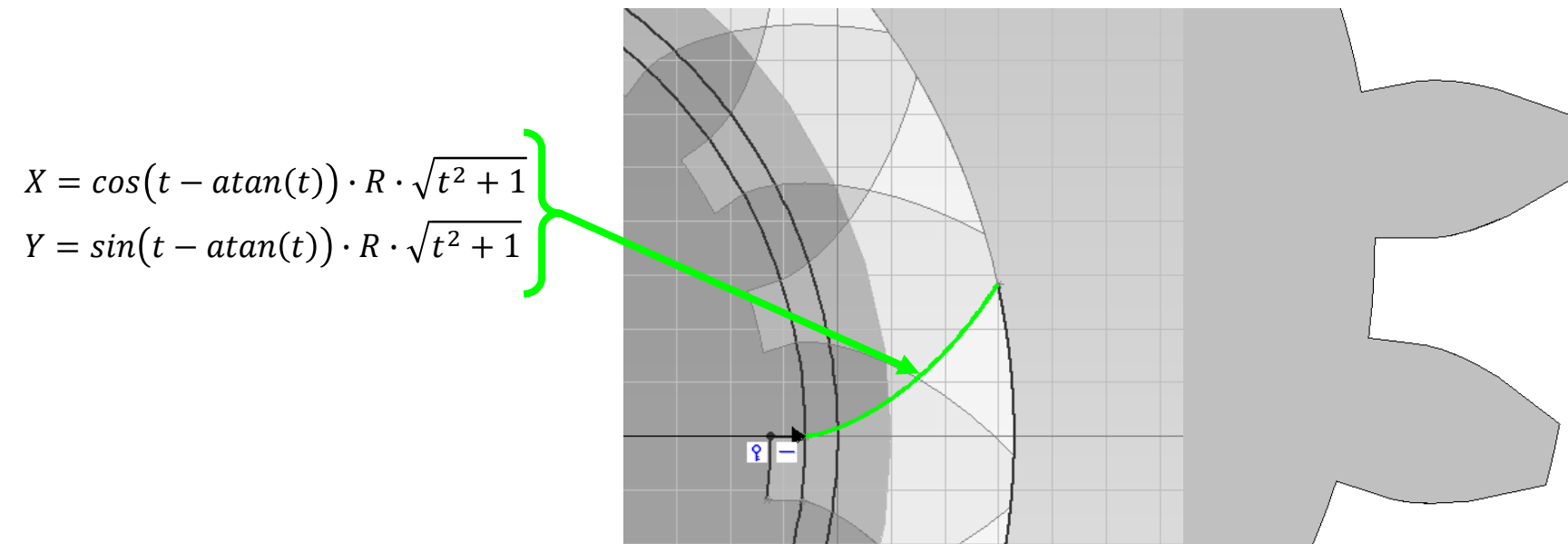
To start a good simulation, it is always better to have a good vision and easy customization of the parts you want to simulate. JMAG V18.0 will help you with that





Complex shape in your geometry

- Function based line drawing allows complex outlines.



Involute gear sketch made possible with the new function.



Shapes created with user defined program

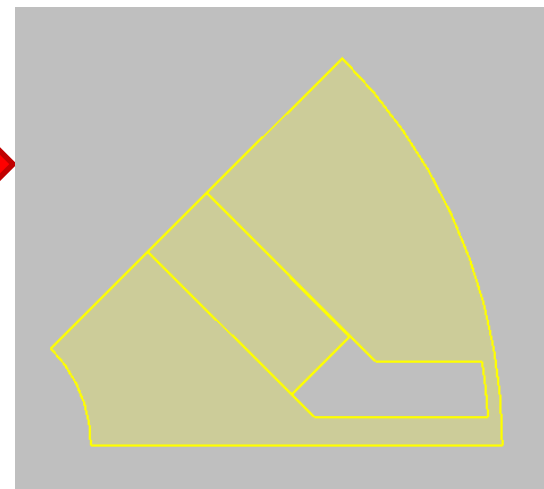
- Geometry templates by modeling API functions (Python)
parametrize the region shape without the burden of constraints.



You can set a Python code that will define your geometry.



General	
Number of Poles [pole]:	4.00000000
Number of coils per pole and per phase [Coil_perPole_perPhase]:	2.00000000
Airgap [Airgap]:	0.25000000
Rotor	
Rotor inner radius [R_in_Rotor]:	5.00000000
Rotor outer radius [R_out_Rotor]:	20.00000000
Magnet span in % [Magnet_Span]:	0.90000000
Radial slit size [Slit]:	0.50000000
Ratio that rotor magnet slot takes [MagnetSlot_Width]:	0.90000000
Thickness of the Magnet [MagnetThick]:	3.00000000
Width of the barrier [BarrierWidth]:	2.00000000
Distance between the magnet and the top of the rotor [MagnetPosition]:	7.00000000
Stator	
Height of the teeth [Height_teeth]:	8.00000000
Back iron [Back_Iron]:	4.00000000
Tooth width [Tooth_width]:	3.00000000
Slot opening ratio [Slot_opening]:	0.30000000
Height of the tooth flange [Height_Flange]:	0.50000000

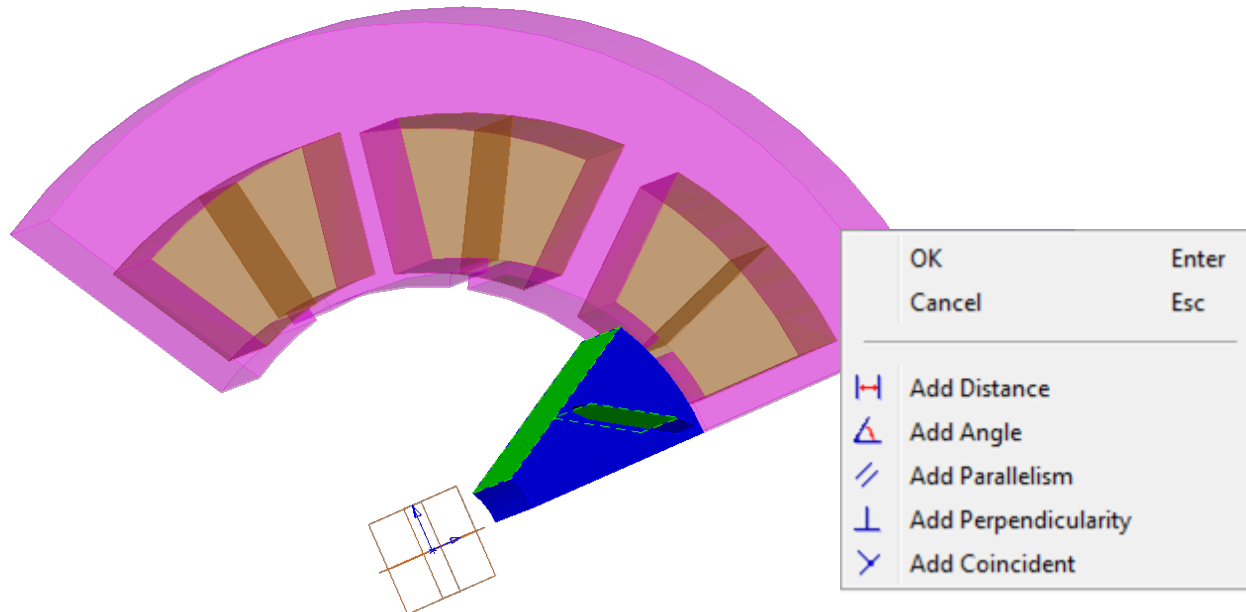


You can easily parametrize your model.

Easy access to direct modelling





**Geometry Editor**

- Context based menu for the direct modelling gives the same usability as the geometric constraints.



Easy to access the direct modelling functionality .

Better visualization of your geometry

New performance improving functions	
Better UI to visualize large models	 JMAG Designer
Select the number of visible digits on constraints	 Geometry Editor
Add labels to your geometry constraints	 Geometry Editor
Add measurements annotation on the geometry	 Geometry Editor

Enhancement of simulations capability

Get a new study type. Reduce your calculation time, reduce your memory usage allow yourself a better handling of large scale models and calculation





Simplify your winding setting

- Parametrized for the winding setting like JMAG-Express.

Winding

Region

Number Of Slots: 24

Number Of Poles: 4

Position Type: Angle

Coil Region 1:

Coil1

Winding

Parallel Number: 1

Series Number: 4

Winding Scheme: Auto

Layers: 1

Coil Pitch: 6

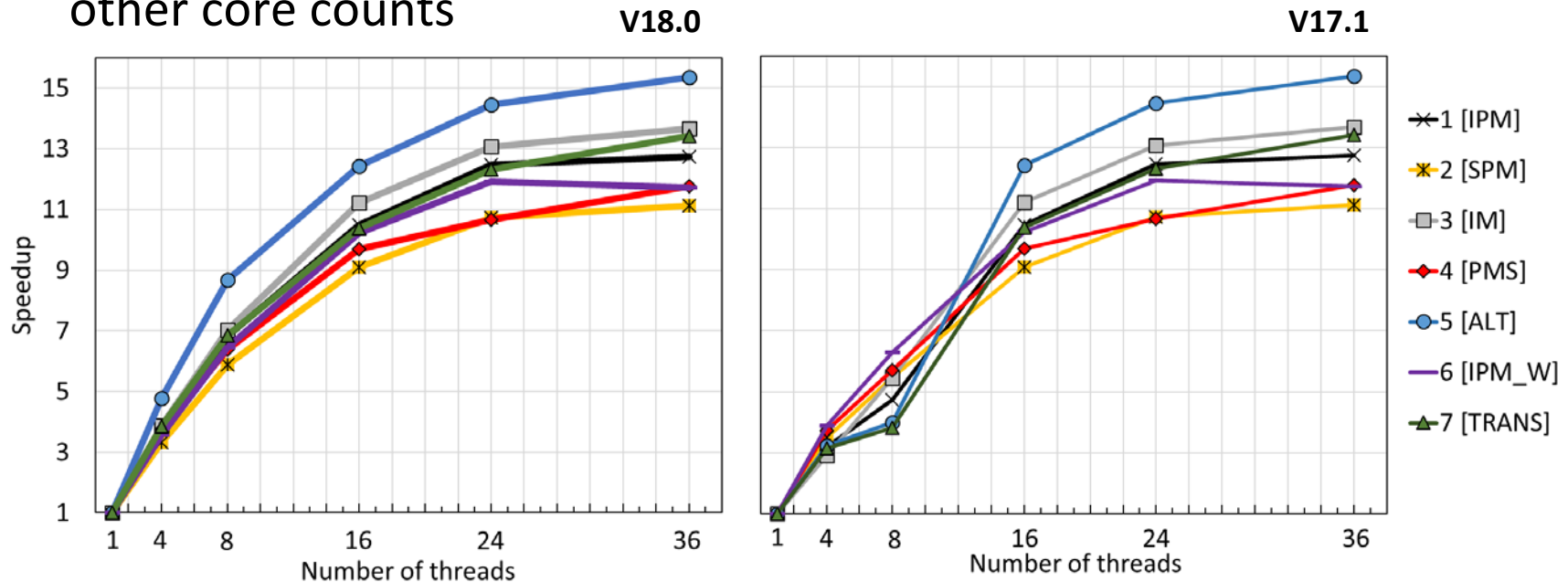
☐ Use Maximum Pitch

Select your winding region, and its parameter to get a winding chart you can customize.



Faster SMP

- The use of SMP at 4 and 8 cores result low speed-up compared to other core counts

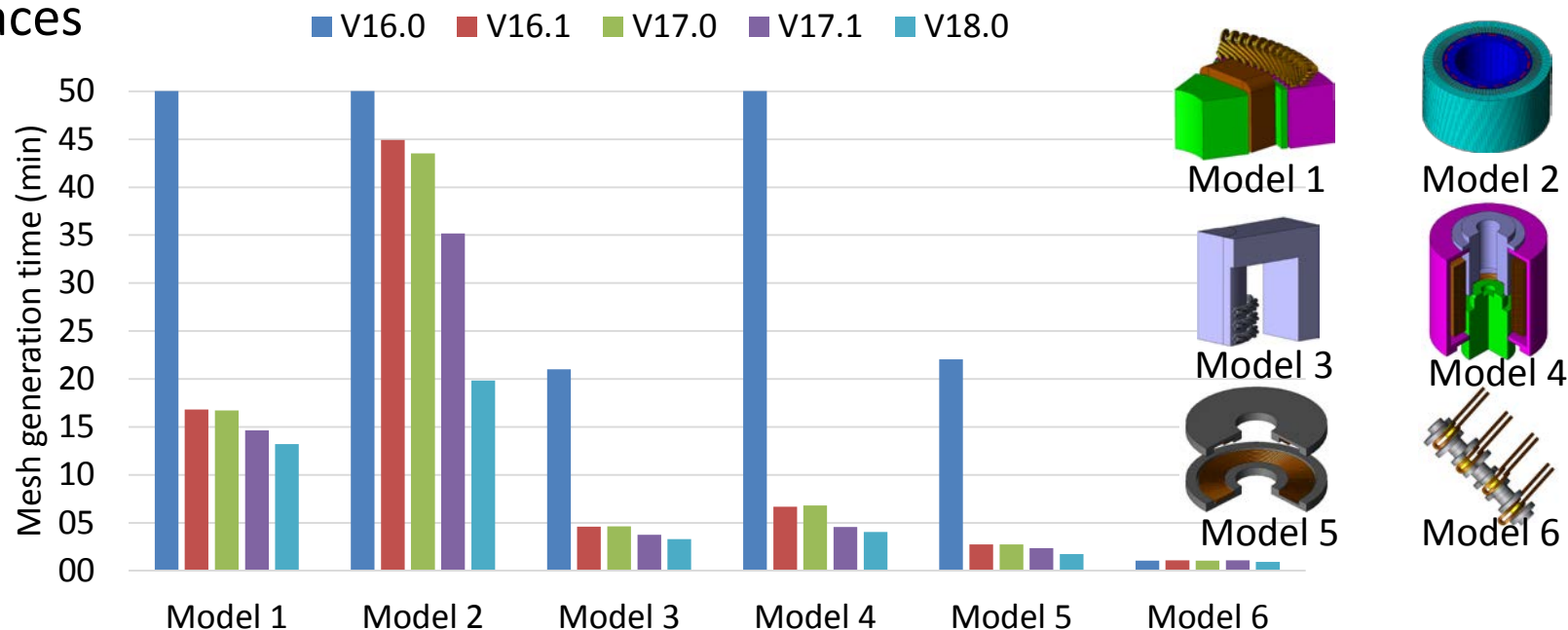


Get a speed increase when using SMP 4 and 8 cores



Speed up your meshing

- Improve the meshing for large scale models with large number of faces

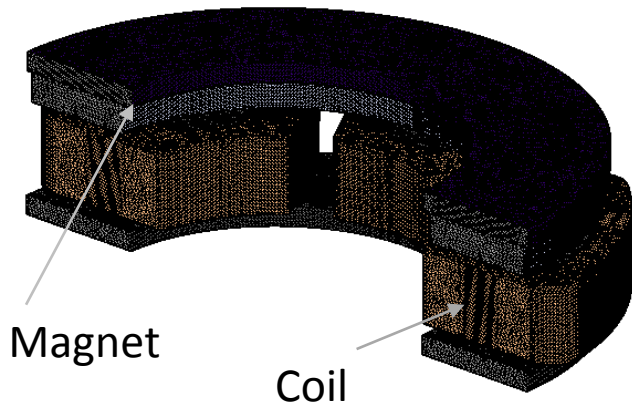


Meshing speed up comparison



Speed-up for models with extended slide mesh

- Remove the need of re-meshing by generating inconsistent mesh



Method	Number of elements	Calc. time (hour)
Conventional	3,675,614~ 3,682,413	12.11
New	3,676,656	9.49

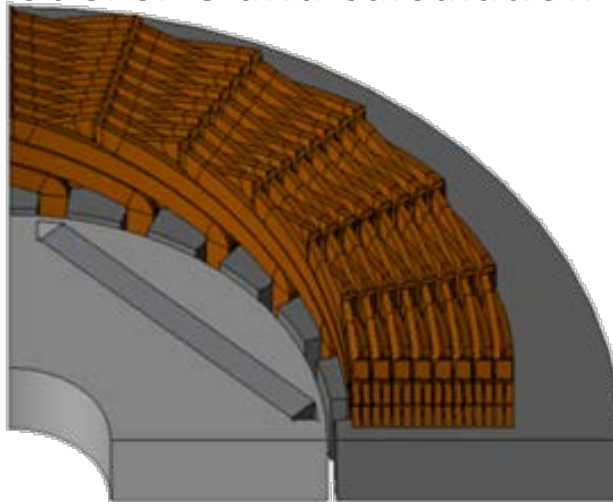
Inconsistent meshing to axial gap motors

By introducing the inconsistent meshing, it can save the time of re-meshing of the extended slide meshing.

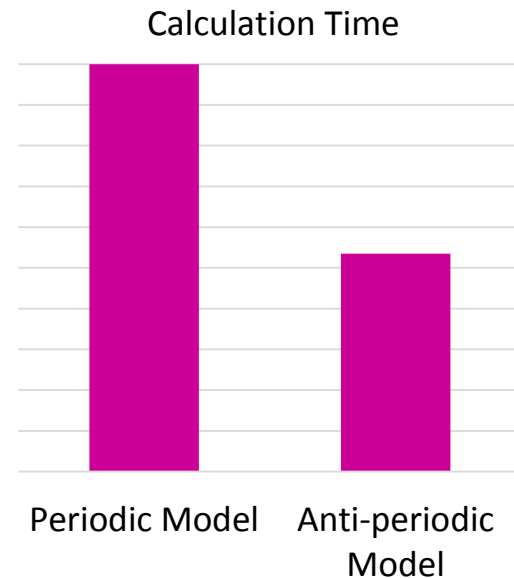


Speed-up your model with FEM conductor

- The support of Ant-periodic boundary condition allow for reductions in model size and calculation time



Square wire model using FEM coils

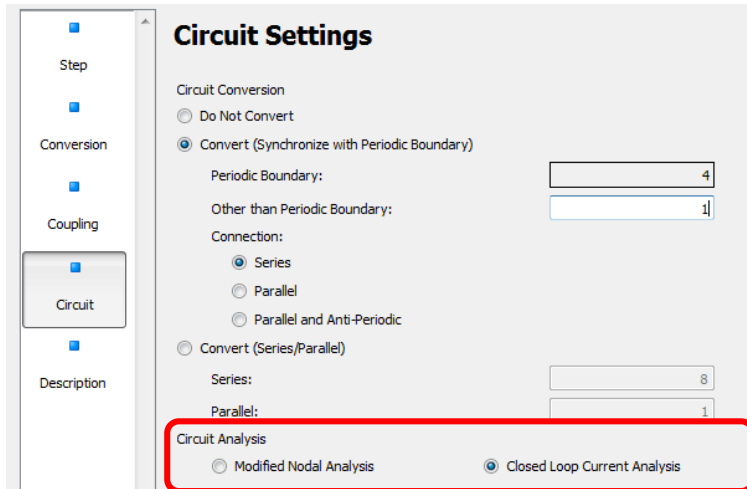


When the periodic boundary condition is used the number of elements is 1,094,932. However it is reduced to 608,006 with the anti-periodic condition.



A new solver to help for convergence

- Some case can have difficulties to converge or take time to converge



Correlation with the Coil type

Type of Coils	Test case number	Cases improved by the Closed Loop Current Analysis
FEM coils	22	9 (41%)
FEM conductors	9	6 (67%)

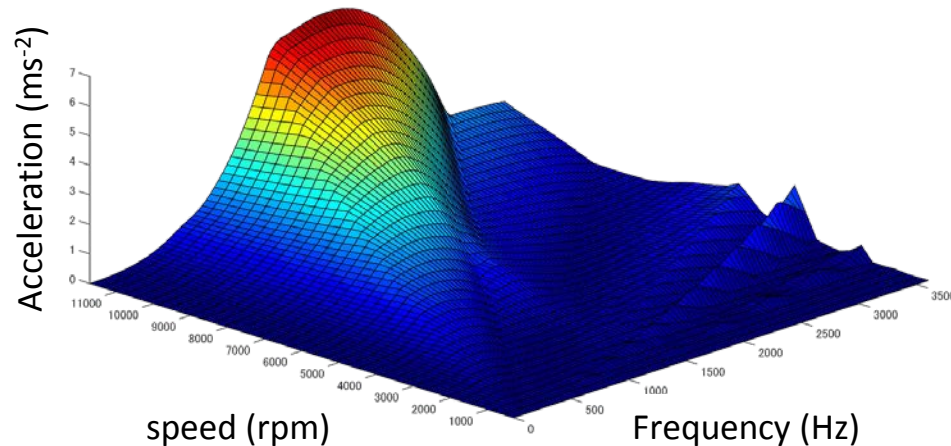
Correlation with the circuit elements number

Number of circuit components	Test case number	Cases improved by the Closed Loop Current Analysis
Less than 10	21	9 (43%)
More than 10	6	4 (67%)

For case with FEM conductors and high number of circuit elements the convergence will be likely improved using the circuit analysis via Closed Loop Current Analysis.

Scale calculated force for different frequencies

- Get the forces for different frequency input without the need for redoing the magnetic field calculation



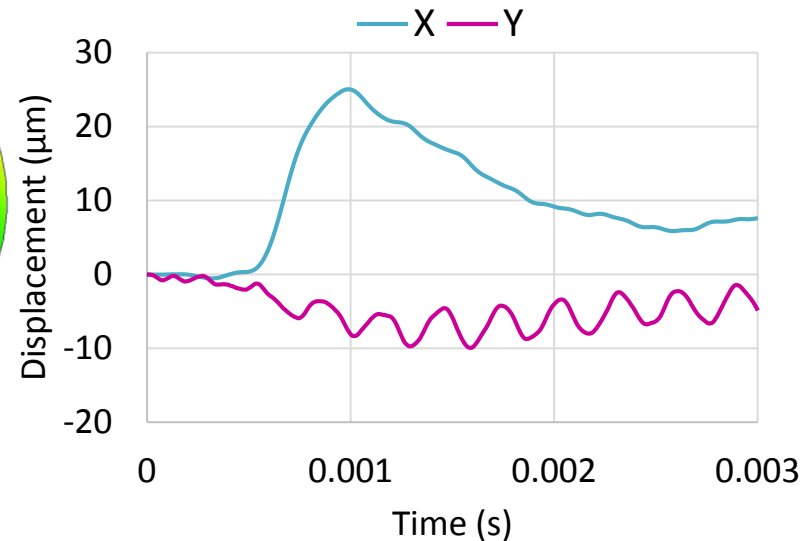
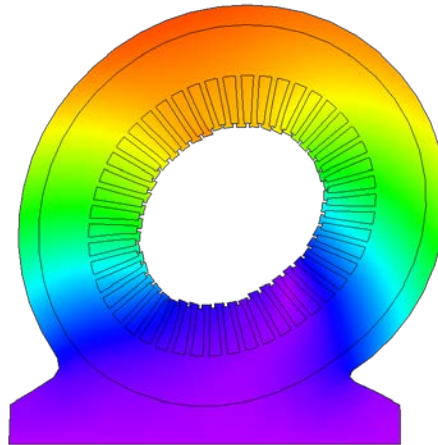
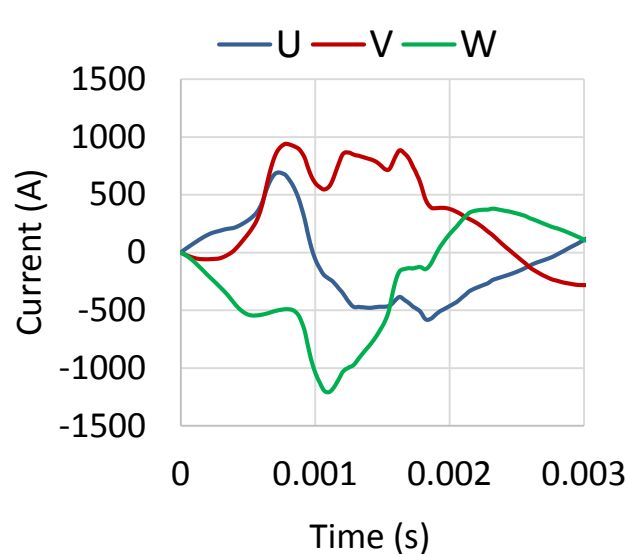
NVH evaluation of a motor via parametric structural analysis

Conventionally, it was necessary to repeat the transient magnetic field analysis, but using a parametric analysis in which the rotation speed is changed by frequency scaling, it is only required once.









Introduction to transient structural analysis

- Evaluate the transient structural deformation due to the starting of a PMSM



The transient currents created by the starting of the machine generate forces on the machine structure that deforms it. When can evaluate this deformation changing with time.

Other performance improvement

New performance improving functions	
A new solver to help for convergence	 Study
Mesh robustness improvement	 Mesh
Restarting adaptive mesh	 Mesh
Change the priority of execution of cases in the scheduler	 JMAG-Scheduler
Iron loss calculation available up 90 millions elements	 Loss
Force mapping in preview for each frequency	 Force mapping

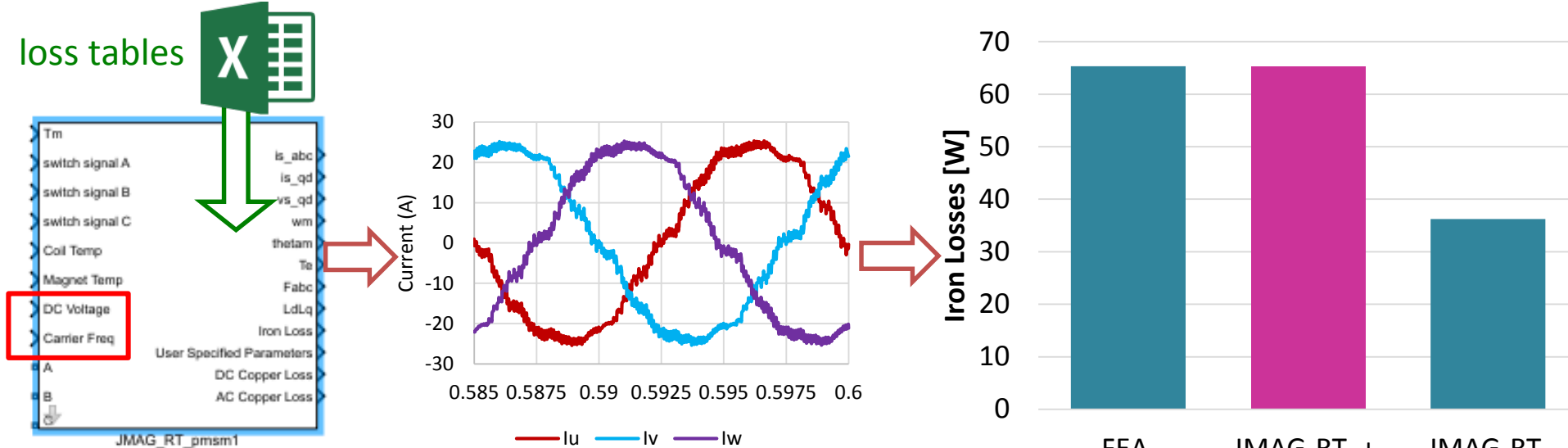
Improvement of JMAG-RT models

For faster model generation as well as an increase in the accuracy of the loss in your JMAG-RT models



Enhancement of loss accuracy

■ Consider of harmonic losses in PMSM and IM

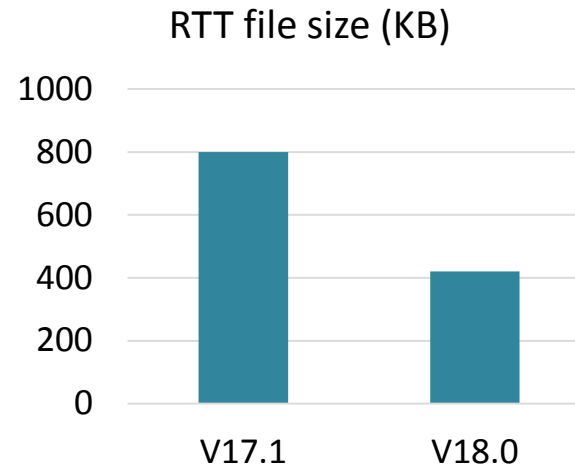
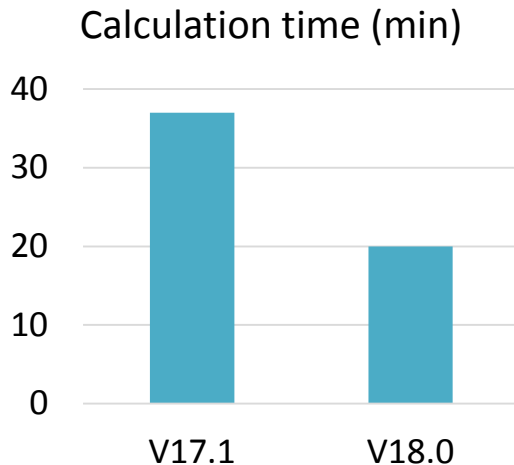


Introduction of detailed loss table:

A detailed loss table is obtained via FEA and added to JMAG-RT as a CSV file. 2 new inputs can be set besides the speed and voltages; carrier frequency and DC voltage.

Shorter JMAG-RT file generation time

- Reduce the number of calculation cases using current phase symmetry
 - PMSM, wounding field synchronous motor, linear machines motor



JMAG-RT developments

New JMAG-RT functions

Wound field synchronous motor

Get a status report on the progress of your JMAG-RT file creation while using SSH

Iron losses on the generic models

Stability improvement of the induction machine simulation

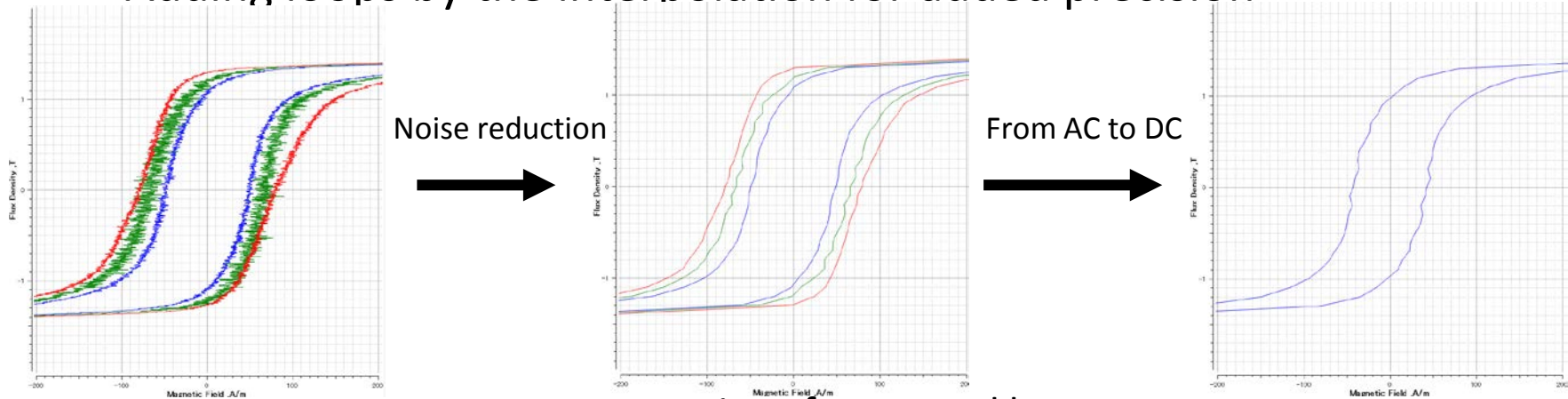
Improve your loss calculations

Better accuracy in you simulation comes with
better calculations of your losses



Tool to create your own data for play model losses

- Reduces the noise of the measured symmetric loops
- Estimates the DC symmetric loops from multiple AC loops
- Adding loops by the interpolation for added precision



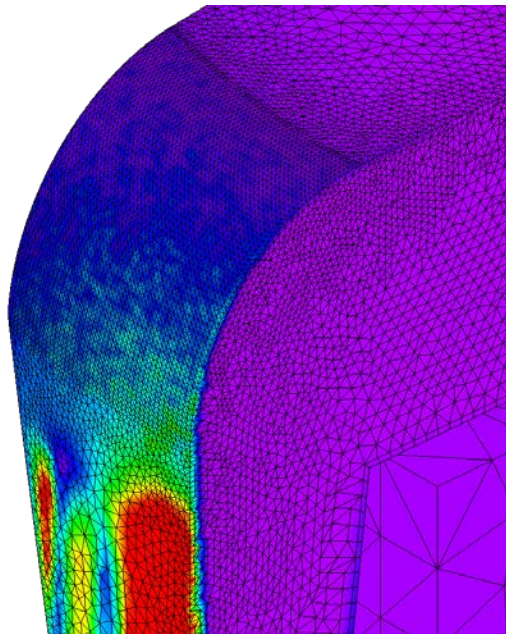
Pre-processing of measured loops

Major loops at 2T are measured at 50,100, and 200Hz. The tool reduces the noise and generate a loop at DC.

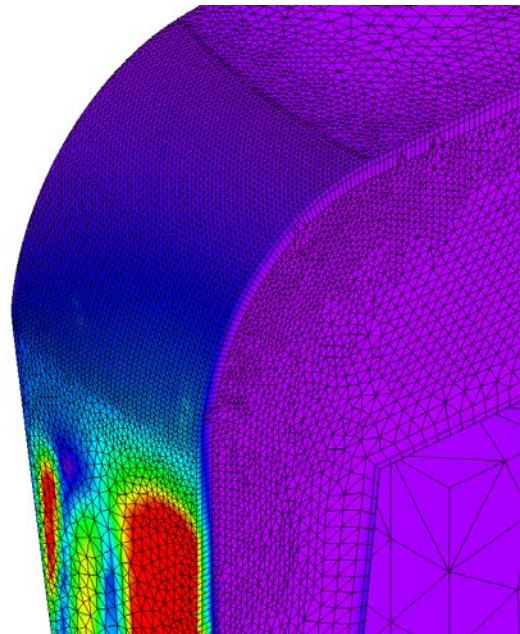


Eddy currents with skin depth mesh in 3D

- Improvement of generation of skin depth mesh under curved faces



Inconsistent mesh around the skin mesh
creates a patchy eddy current density

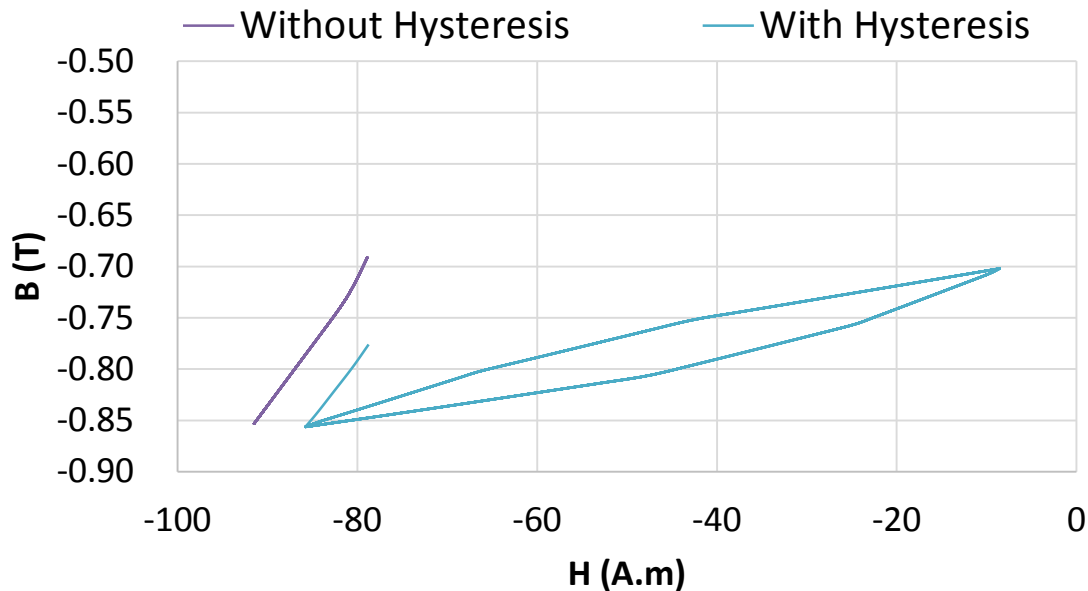
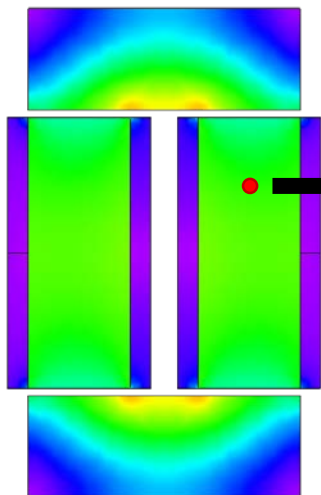


Smoother eddy current loss density due to
proper skin depth mesh generation (V18.0)



Hysteresis losses on 3D models

- The use of play models for accurate hysteresis losses



You can now have access to take in account the effect of the hysteresis losses during the calculation and not only just during the post-processing.

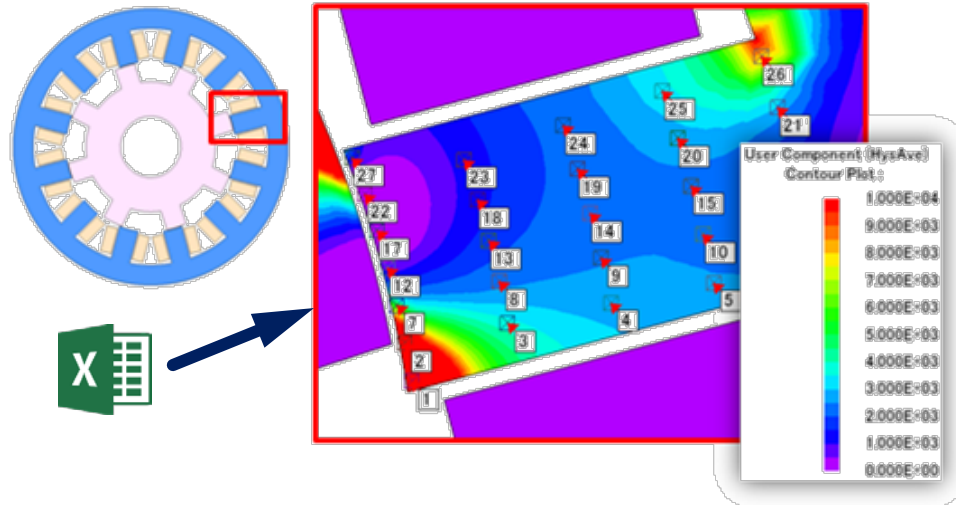
Better parameter handling and enhanced optimisation capability

Get more flexibility with your outputs and parameters. Have a better vision and efficiency of your optimisation. Get a whole new way to do optimisation in JMAG



Split the CSV output

- To confirm the loop in the teeth of a machine would require a large amount of probes. Set them manually would be time consuming

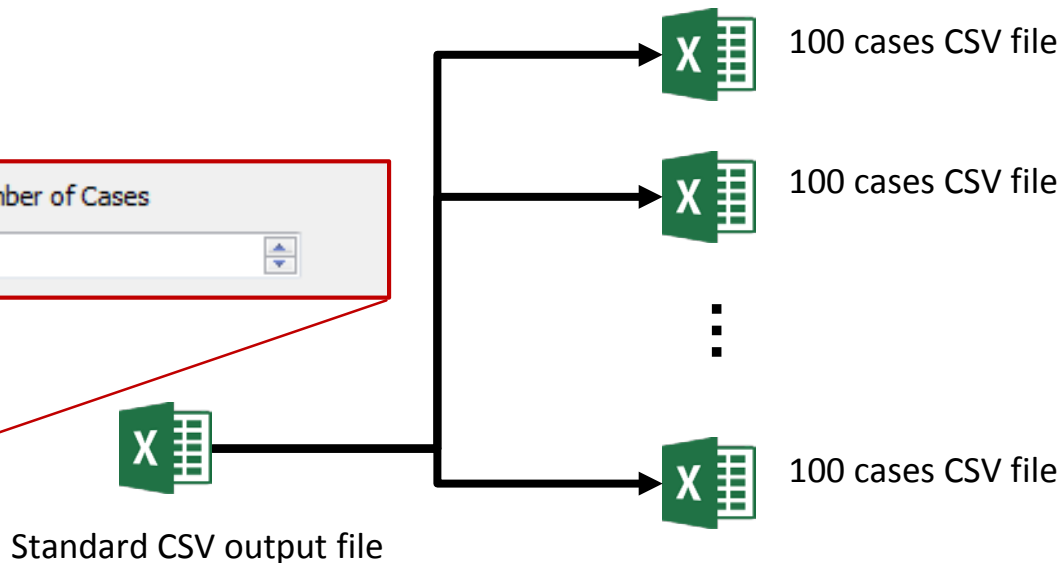
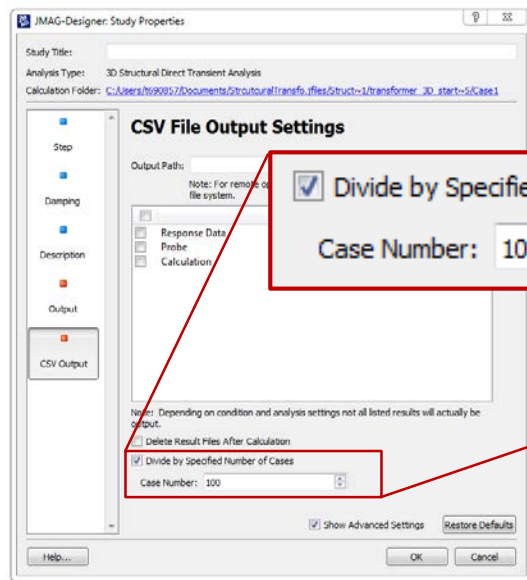


Set of probes via a CSV file to observe the hysteresis loops at different position in the teeth.



Separation of CSV Outputs

- The CSV output of large scale calculation can be difficult to post process



You can separate the csv output files by a certain amount of case.

Response Data for parametric optimisation



Response Data

New Response Data

Outputs set in any coordinates system you need

Output the area or volume of parts of your geometry

Output of complex number can be set in polar form

Line to Line voltage can now be exported as response data into CSV files

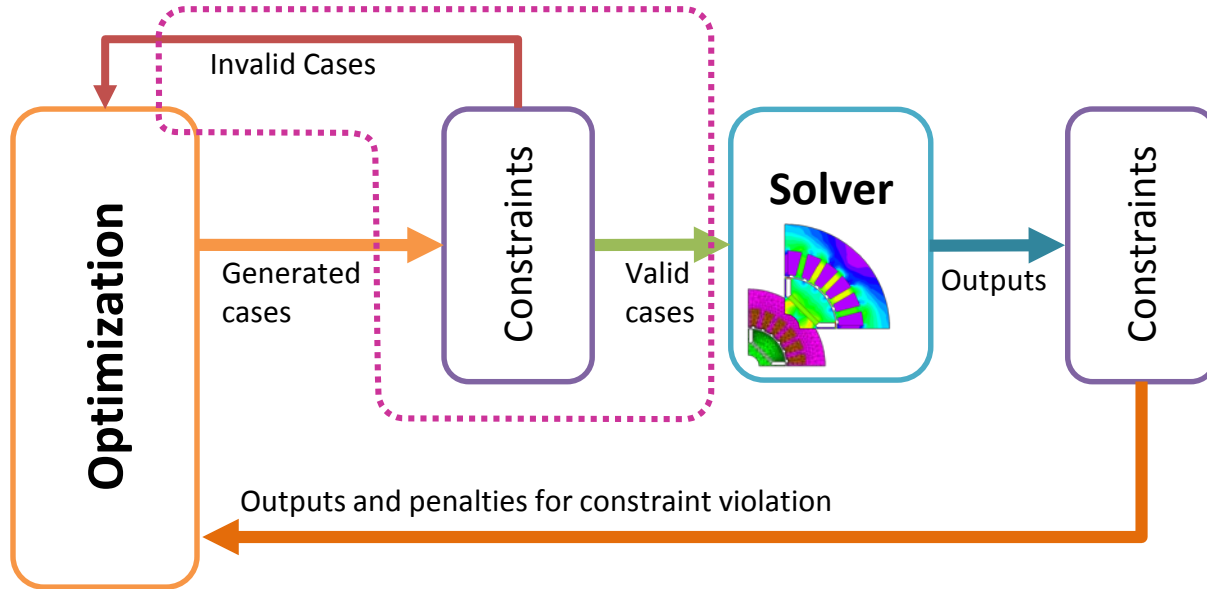
Output the average temperature of grouped parts



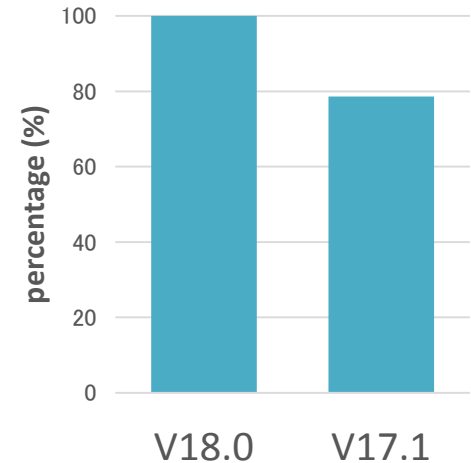
Improvement of optimisation efficiency

- Skip calculation of cases that do not satisfy constraints

New Step in the Optimisation process



Percentage of run cases that satisfy constraints on CAD parameters



Reduction of unnecessary calculation time and improvement of the optimisation's efficiency.

Keep an eye on your submitted optimisation

- You can now export Objectives functions with the response Data
- The timing of the update of the CSV files can be changed according to the needs

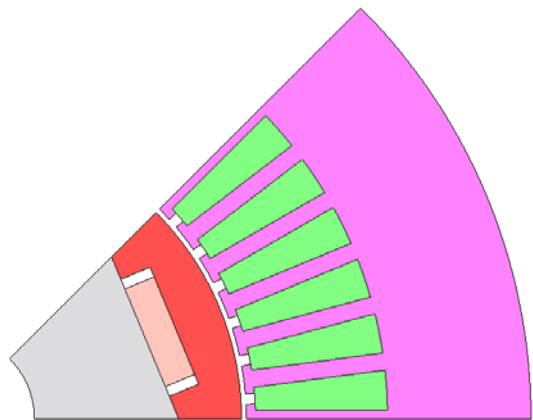
	A	B	C	D	E	F	G	H	I	J	K
1	Case	Obj A	Obj b	Obj c	T	Loss	Other	a	b	c	d
2	1	-	-	-	-	-	-	-	-	-	-
3	2	0.4807	0.380836	0.131147	0.015743	0.976434	0.393066	0.041552	0.367983	0.428894	0.080029
4	3	0.431391	0.093614	0.147422	0.771917	0.698966	0.760017	0.048498	0.085674	0.982002	0.699409
5	4	0.224167	0.459357	0.810402	0.505816	0.45491	0.892577	0.992754	0.827355	0.932694	0.806687
6	5	0.226894	0.713508	0.317899	0.284757	0.741043	0.202487	0.534892	0.178022	0.912759	0.362971
7	6	0.43841	0.294803	0.495594	0.753284	0.718092	0.39654	0.292836	0.646776	0.346416	0.571331
8	7	0.562329	0.739856	0.224752	0.034783	0.4821	0.221852	0.555415	0.090495	0.574607	0.342626
9	8	0.511993	0.433951	0.871429	0.448752	0.504835	0.974373	0.217461	0.043341	0.307987	0.138944
10	9	0.652035	0.571528	0.487579	0.338235	0.627718	0.067897	0.913924	0.321168	0.608989	0.461366
11	Objectives			Response Values			Parameters				
12											

Example of output file given by the optimisation



Topology optimisation available in JMAG

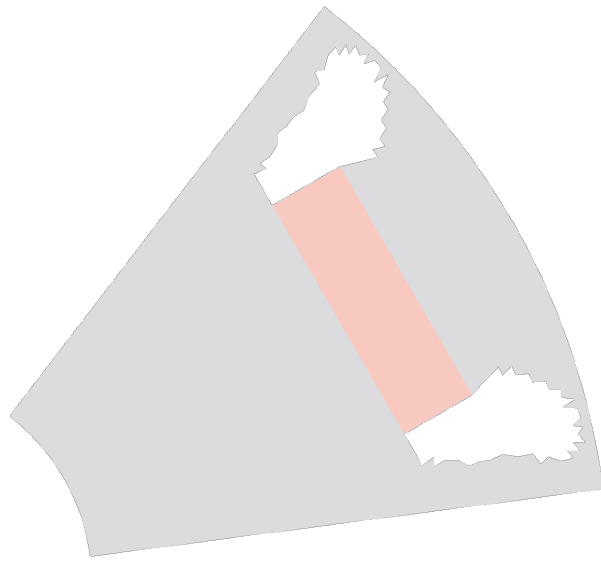
- Use an ON/OFF method to optimise shapes



Selected design space



Resulting optimized topology



Rotor shape optimisation. The material of each element of design zone is changed by the optimisation to maximize the torque.

Think your JMAG circuit differently

Your JMAG circuit is now much more!

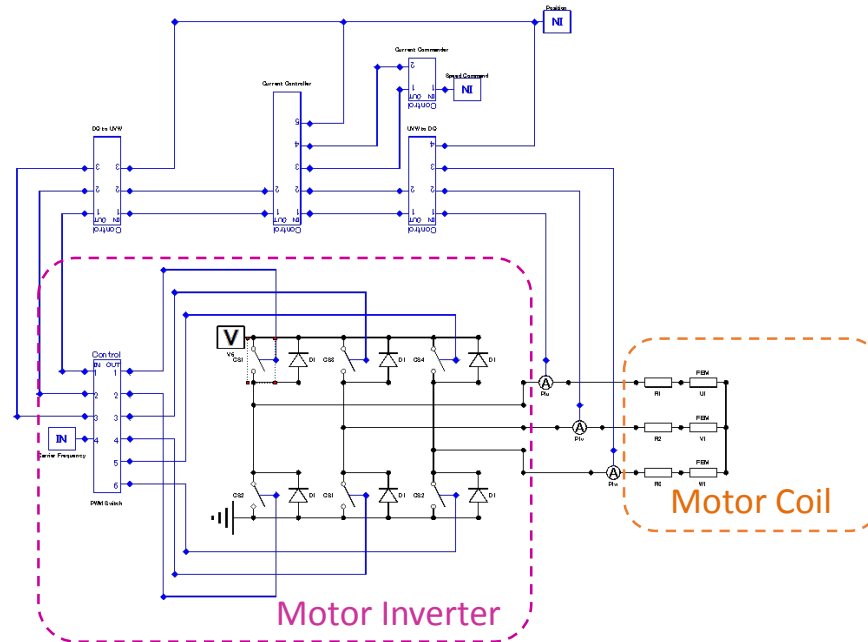
Welcome Control in JMAG





Use control circuits without external software

- Introduce control circuit in its JMAG circuit:


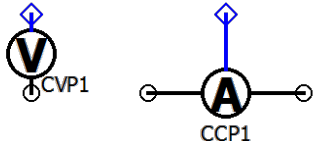

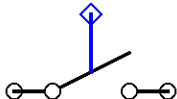
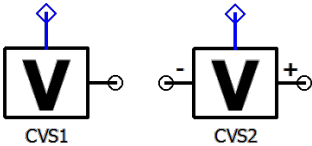

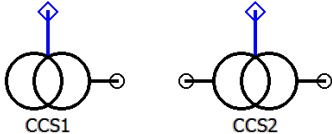
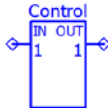


Motor drive system

The black lines represent the power circuit. The blues ones the control signals.

Control Components list



Name	Component	Name	Component
Control Input	 CIB1	Control voltage and current probe	
Control Output	 COB1	Controlled switch	 CS1
Controlled voltage source		Control signal probe	
Controlled current source		User defined macro via python files	 CCB4

Control pre-defined components (1/2)



Functions	
Abs	Diff
Add	Divide
Atan	Gain
Cos	Product
Sin	Sqrt
Transfer Mechanical angle to electrical angle	Branch
1D Look-up table	2D Look-up table

Control pre-defined components (2/2)

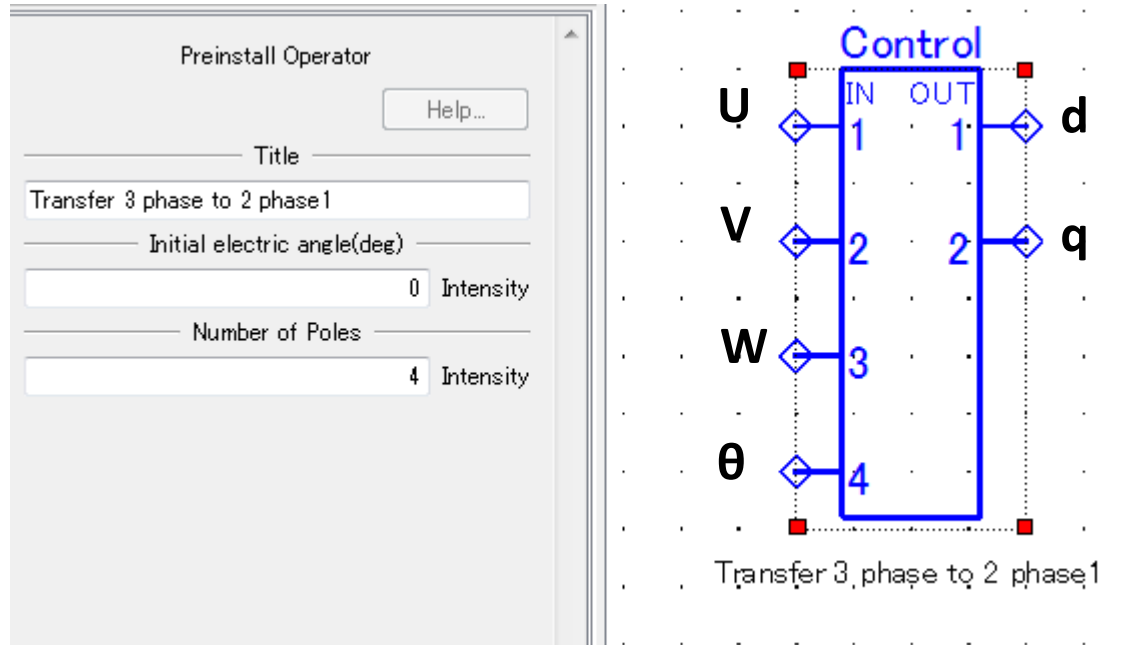


Functions	
Sine wave	Step
Ramp	Triangle wave
Sawtooth wave	Comparator
Saturation	Zero Order hold
Dead time	PWM



DQ transformation as predefined component

- The use of 3 phase signals can sometimes be laborious

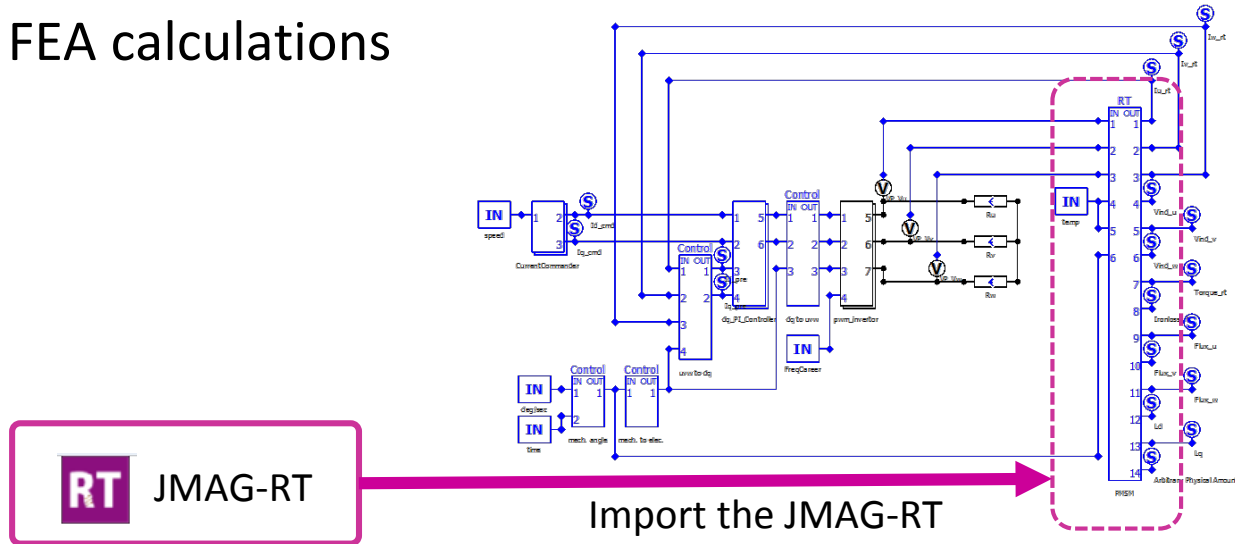


JMAG circuit has a dq (Park) component to convert the signals



Use your JMAG-RT models in JMAG-Designer

- Use control systems with your JMAG-RT models and combine them with FEA calculations



RT

JMAG-RT

Create an JMAG-RT
model of your model

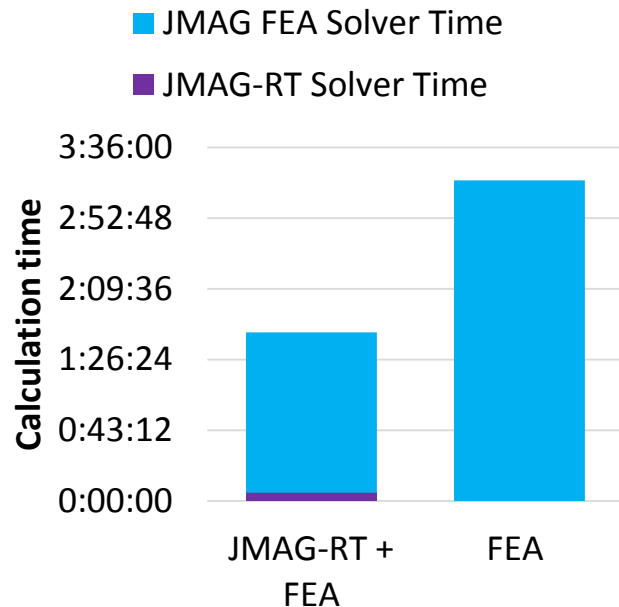
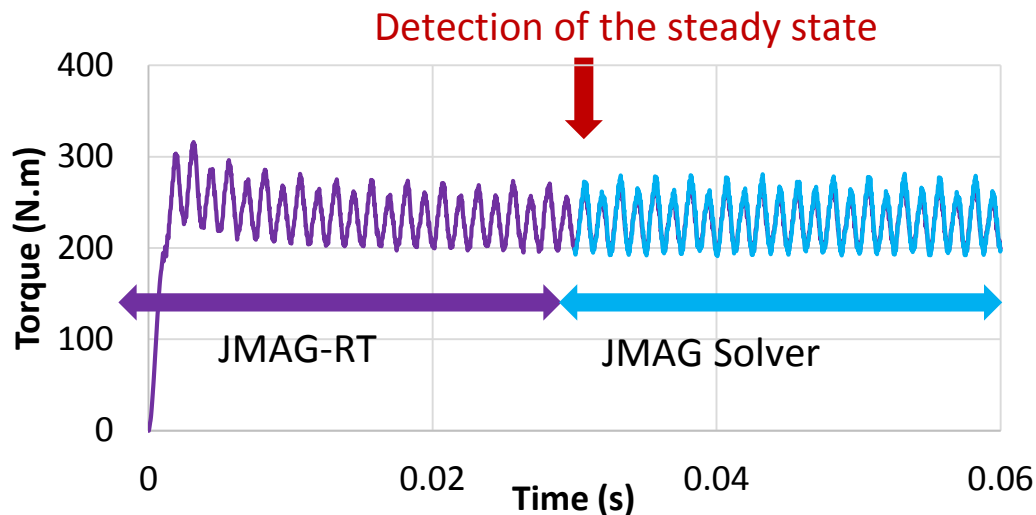
Import the JMAG-RT
model into a circuit

You can use your JMAG-RT file in your JMAG circuit.



Steady state detection tool

- Reduce the calculation of your control system FEA calculations



You can use the JMAG-RT model of your design to reach the steady state of a selected operating point. Then only run the FEA study on the steady state.

Efficiency maps directly in JMAG-Designer

Evaluate your machine's performance a not only on one operating point but on its full operation area

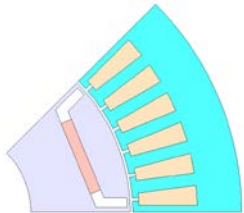




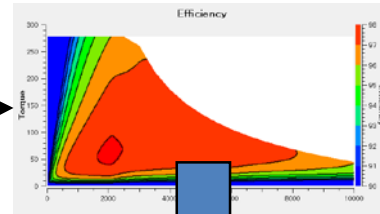
Efficiency map evaluation function

- Speed priority (parametric mode)
- Precision priority (high accuracy mode)

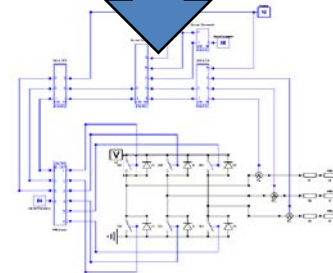
Speed priority



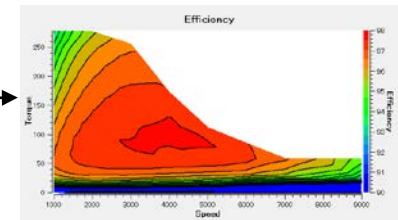
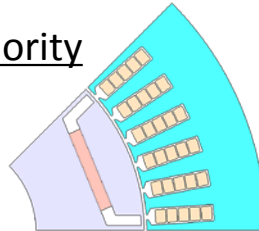
Response Table
(Motor characteristic
mapping)



Current vector for each operating point



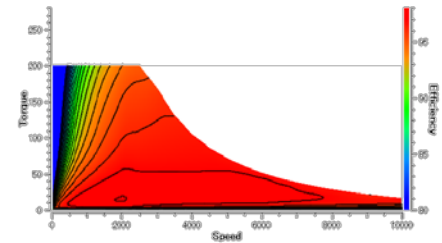
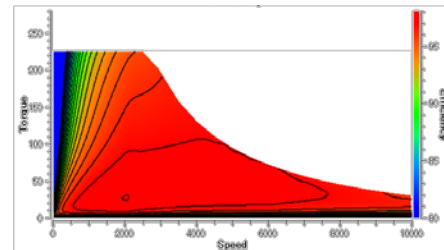
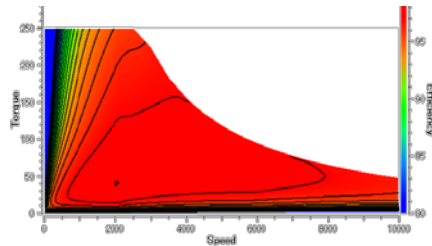
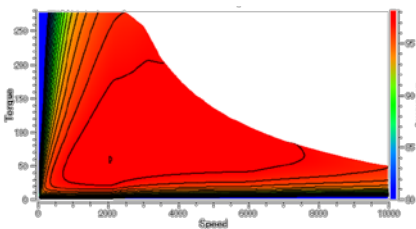
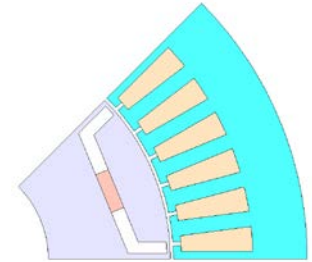
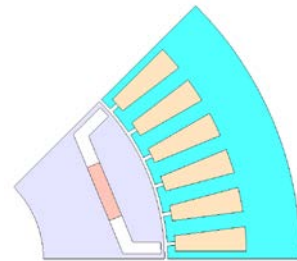
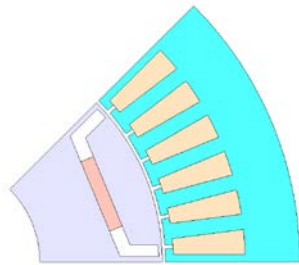
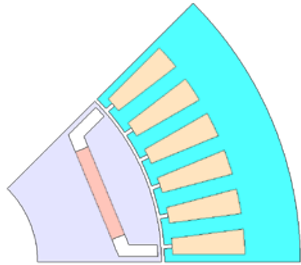
Precision priority



Speed priority (parametric mode)



- Fast generation of efficiency maps for each shapes of potential designs

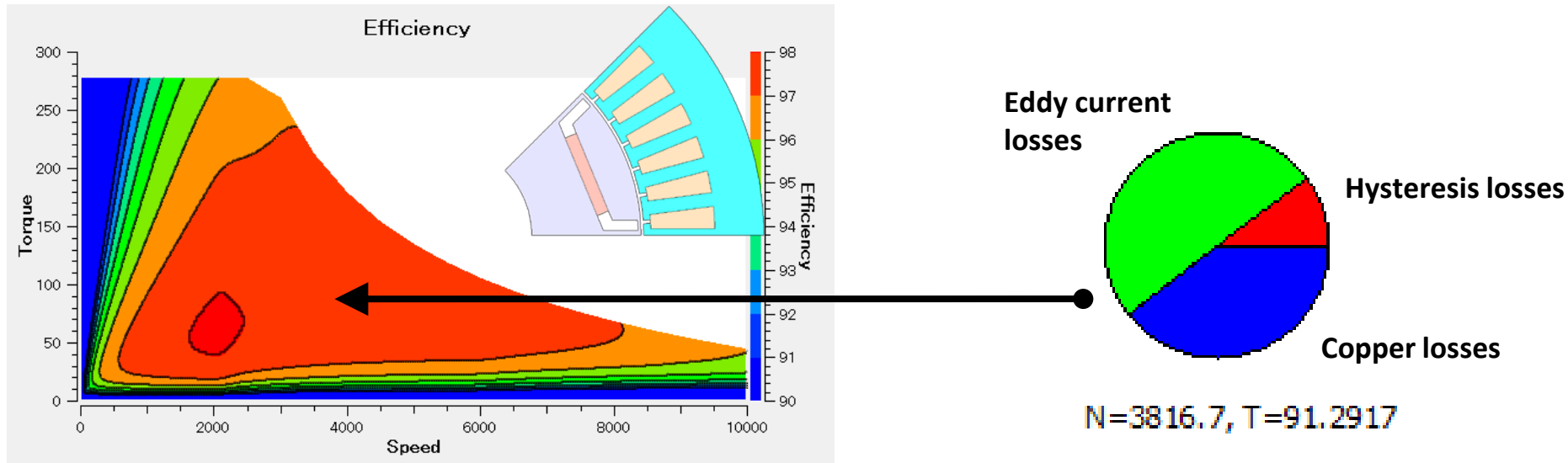


Parametric analysis of efficiency maps with changing magnet width

Efficiency map directly with JMAG Designer



- Breakdown of the losses for each operating point can be displayed in one click



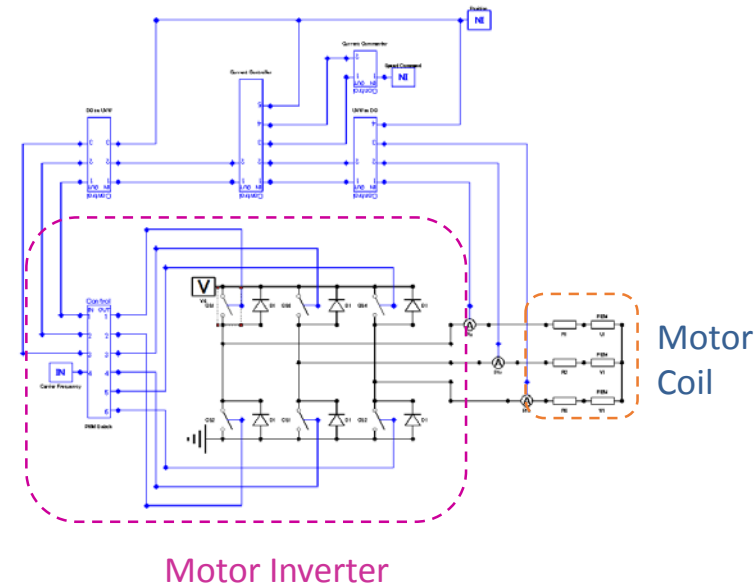
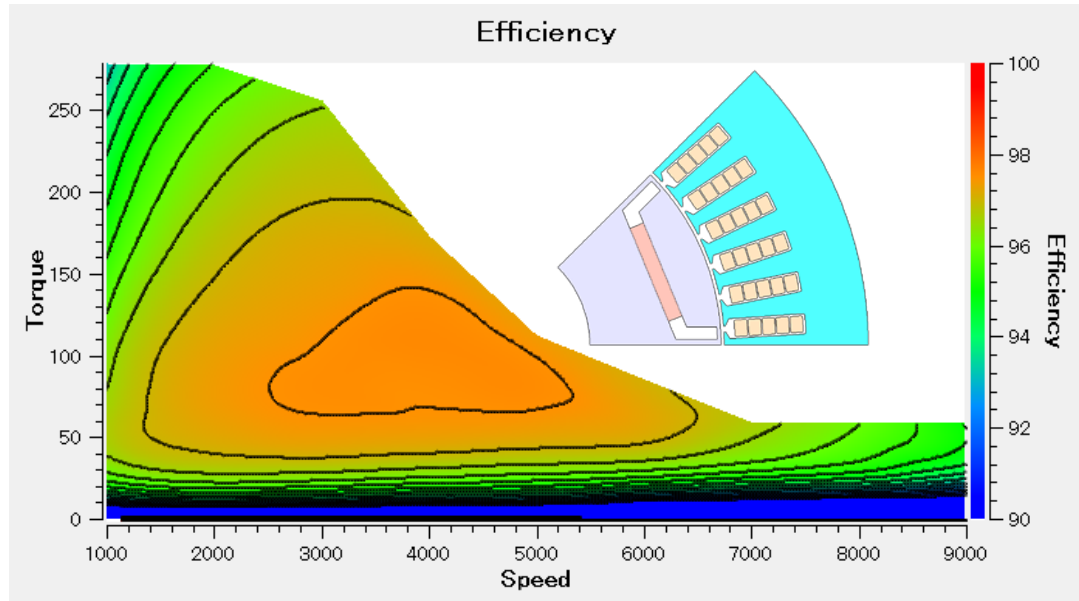
Example of efficiency map and the losses breakdown for one operating point



Efficiency map

High accuracy efficiency map

- The efficiency map can be improved by adding the effect of the control system

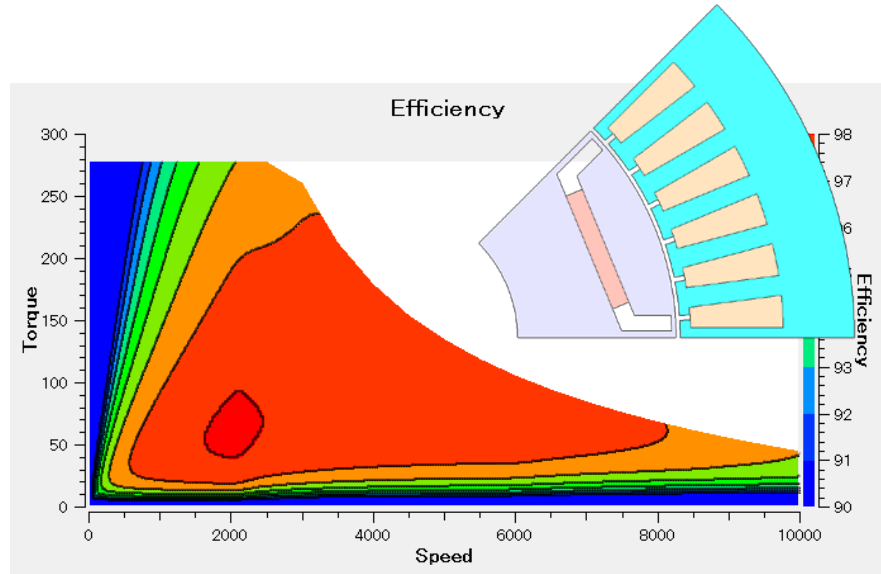


Get high accuracy efficiency maps can be obtained

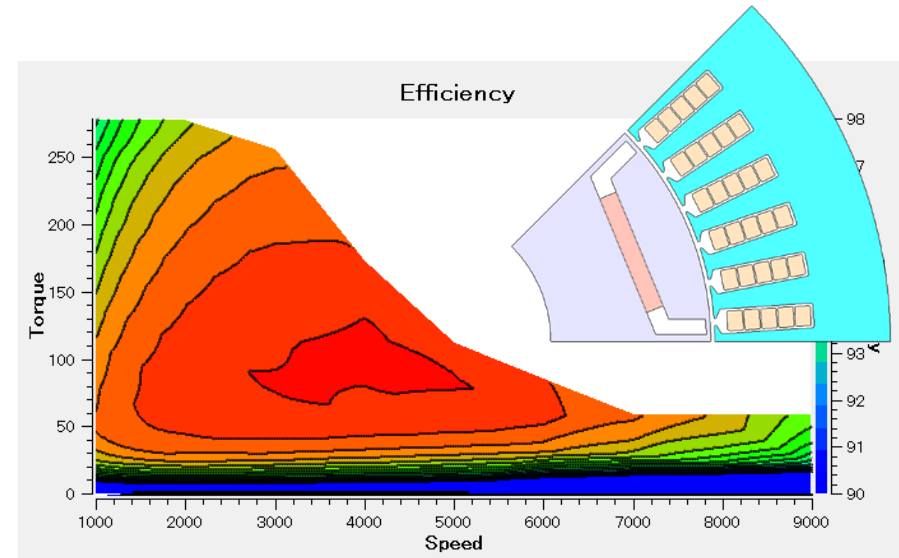
Precision priority (high accuracy mode)



- Efficiency map including harmonics and AC losses with PWM



AC losses ignored and sinusoidal waveform



AC losses included and PWM waveform

Comparison of efficiency maps for models with different degrees of precisions

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