SmartCtrl ^{4.1}

What's new

All compensators









$\begin{array}{c} \label{eq:constraint} \begin{array}{c} \mbox{there} \mbox{ther$

All in Z domain

01

Analog or Digital?

Type I,

II & III

Analog predefined compensators

 Digital predefined compensators



Z domain

User defined compensators, with automatic parameter identification, applying all the SmartCtrl compensator tuning algorithms to the user design

Just select the checkbox to define which solution you need.

PI

& PID



In order to define a real DIGITAL control, SmartCtrl works directly in Z domain.

Power converter new modelling approach is based on multivariable z-domain models.

SmartCtrl allows the designer to work with discrete models to **get the best performance and the highest bandwidths** for the digital control loop. Improve your design compared to S discretized models.

Plant, sensor and compensator can be defined in:



• Z Z Z, Plant in Z domain, Sensor in Z domain and Compensator in Z domain

SSZ, Plant in S domain, Sensor in S domain and Compensator in Z domain



UZ

What's new

SmartCtrl ^{4.1}

03

Open... Seven Savem...

// Plant transfer function Gd = Vin / (L+C+s+s + (L/R)+s + 1) return Gd

et.defaults Editor... Compile Castro

Initial Requests (14) Entransis (14)

Select parameters

Help Cancel OK

New parameter sweep and Check for updates

Just click in the **Select parameters** button and SmartCtrl will automatically detect the parameters in the transfer function defining the plant, sensor or compensator in the Equation Editor.

Save time and effort to get the best possible solution.

New Check for Software updates option to look for new SmartCtrl releases.

🔕 SmartCtrl: The ultimate control design tool for power electronics

After over 20 years of experience in the field of power electronics systems SmartCtrl software is being developed as a platform in which, our knowledge related to control in power electronic systems, is collected.



SmartCtrl can solve the control design problem for **ANY** power converter. From the most simple **DC-DC** model using a basic template to the most complex PFC Boost converter with a double control loop, just from the design specifications.

The final result from SmartCtrl is the control design (ready to be exported and simulated in PSIM) and all the compensator parameters (Analog or Digital). **Complete converter, control loop and magnetics design for the most common topologies.**

Use the **import frequency response** option to get your plant transfer function into SmartCtrl, then continue with the guided control design process to get the best control for your system.



